## INSTRUCTION MANUAL

## Control Unit

Model 780

## CONTENTS



| Figure No. | Title | Page |
| :---: | :---: | :---: |
| 1 | Front Panel . | 1-2 |
| 2 | Rear Panel . . . . . | 1-2 |
| 3 | Installation of Series 7801, 7802, 7819-1EC and 7813 Cards. | 2-3 |
| 4 | Installation of Dual Control Unit Coupler (Model 7819-DCC). | 2-4 |
| 5 | Top View of Control Unit With Cover Removed . . | 2-6 |
| 6 | Card-edge Connector (J101, J102, or J103) . . . | 3-2 |
| 7 | Scanner Connector ( $\mathrm{P} \mid 10$ ). . . . . . . . . . | 3-3 |
| 8 | Front Panel Indicators. . | 4-6 |
| 9 | Trace for Test \#1. . | 5-2 |
| 10 | Trace for Test \#2 . . . . . . . . . . | 5-3 |
| 11 | Trace For Test \#3 . . . . | 5-4 |
| 12 | Trace For Test \#4. | 5-5 |
| 13 | Trace For Test \#5. | 5-6 |
| 14 | Trace For Test \#6 | 5-7 |
| 15 | Trace For Test \#7. . | 5-8 |
| 16 | Trace For Test \#10. . | 5-11 |
| 17 | Trace For Test \#11. | 5-12 |
| 18 | Trace For Test \#13. | 5-15 |
| 19 | Trace For Test \#14. . | 5-16 |
| 20 | Trace For Test \#15. . | 5-17 |
| 21 | Trace For Test \#16. . | 5-18 |
| 22 | Trace For Test \#19. | 5-24 |
| 23 | Trace For Test \#20. . . . . . . . . . . . | 5-25 |
| 24 | Trace For Test \#21. . . . . . . . . . . | 5-26 |
| 25 | Trace For Test \#22. . . . . . . | 5-27 |
| 26 | Rack Mounting of the Control Unit . . | 6-1 |
| 27 | Multi-Scanner Coupler (Model $7819-\mathrm{MSC}$ ) | 6-2 |
| 28 | Typical System 1 Multi-Scanner Connection. | 6-3 |
| 29 | Custom Interface (Model 7802-CIK) . . . . | 6-6 |
| 30 | Chassis Assembly. . . . . . . . . | 7-3 |
| 31 | Component Layout For PC-395. | 7-11 |

## SPECIFICATIONS

GENERAL: Holds up to three System l Instrument Interface or special-purpose cards. Supplies power to cards. Captive cable plugs directly into the System 1 Programmable Calculating Unit.
DISPLAY: 18 LED lamps indicate the last Output 8-bit word transferred, the next 8-bit word to be Input, and whether the last word transferred was Data or Control.
CONTROLS: Front panel power switch. Internal switch sets Control Unit address. 702/702X INTERFACE:

GENERAL: Built-in interface connects directly to one Model 702/702X 10channel Scanner, or with 7819-MSC, to as many as eight 10-channel Scanners for random access to single channels. For parallel-channel or matrix operation, one channel on each Scanner may be selected.
OUTPUT INSTRUCTION:
Control Transfer: Deactivates all or selectively activates one of up to 80 channels.
Power up/Reset: All scanner channels off.
Nominal Instruction Time: 70 milliseconds.
ISOLATION (PCU GROUND TO ANALOG LO): Provided by Model 702 X plug-in cards.
ENVIRONMENT:
OPERATING: $0^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}$ up to $80 \%$ relative humidity. STORAGE: $-25^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$
POWER: $90-110,105-125,210-250$ volts (switch selected), $50-60 \mathrm{~Hz}, 50$ watts.
DIMENSIONS, WEIGHT: 3-1/2 in. full rack, overall bench size 4 in . high $\times 17-1 / 4$ in. wide $\times 15-1 / 2 \mathrm{in}$. deep ( $105 \times 440 \times 395 \mathrm{~mm}$ ) ; $5 \mathrm{ft} .(1-1 / 2 \mathrm{~m}$ ) captive cable to PCU . Net weight, 13 pounds $(5,8 \mathrm{~kg})$.
ACCESSORIES FURNISHED: Hardware for standard $3-1 / 2 \mathrm{in} . \times 19 \mathrm{in}$. rack mounting. 15-1/2.in. ( 395 mm ) depth behind front panel.

1-1. INTRODUCTION. The Model 780 Control Unit provides the link between the Programmable Calculating Unit (PCU) and all other instrumentation in the System 1. The Control Unit may be used with up to three Instrument Interfaces or other devices and eight Scanners. (A PCU and appropriate $1 / 0$ Handler Software is needed to communicate with the Control Unit.)
Instrument Interfaces may be installed in any of three rear panel plug-in compartments or "slots". The locations of the Instrument Interfaces are labeled as Interface Number 1, 2, arid 3.
Scanner interface circuitry is built into each Control Unit. The rear panel "SCANNER" connector mates with a System Interconnect Cable (Model 7021-2) furnished with the Keithley Model 702 Scanner.

When a Multi-Scanner Coupler is connected to the Control Unit, up to eight Scanners ( 80 channels total) may be used. Each Scanner connects to the MSC via individual System Interconnect Cables.
The Control Unit has 18 indicators on the front panel which display pertinent information as to the status of System 1 operations.
-INPUT Indicators: These indicators represent an 8-bit word to be transferred from the Control Unit to the PCU.
-OUTPUT Indicators: These indicators represent an 8-bit word which has been transferred from the PCU.

- DATA Indicator: This indicator identifies the last 8 -bit word transferred as DATA. -CONTROL Indicator: This indicator identifies the last 8-bit word transferred as a CONTROL byte.

In a System 1/782-XY, two Control Units are used. In this configuration an internal switch on each Control Unit is used to identify Control Unit \#l (CUI) and Control Unit \#2 (CU2) in the System. This identification enables the user to communicate to either Control Unit via 1/0 Hander Software. A Dual Control-Unit Coupler must be installed on either Control Unit CUI or CU2 to facilitate connection of a second Control Unit. The Control Units may be rack mounted using hardware furnished. The captive cable on the Control Unit is five feet long and mates with a $37-\mathrm{pin}$ connector on the PCU or 2nd Control Unit. Cabling to instrument or other devices is furnished with individual Instrument Interfaces.
1-2. WARRANTY INFORMATION. See GUIDE TO USING THE SYSTEM 1 for detailed information.
1-3. CHANGES. Improvements or changes to the Control Unit which are not incorporated into the INSTRUCIITON MANUAL can be found in the System 1 Instruction Manual Addenda.

figure 1. Front Panel.

figure 2. Rear Panel.

SECTION 2. INITIAL PREPARATION

2-1. GENERAL. This section provides information needed for incoming inspection and preparation for use.

2-2. INSPECTION. The equipment furnished was carefully inspected both mechanically and electrically before shipment. Upon receiving the equipment, check for obvious damage which may have occured during transit. Report any damage to the shipping agent and your Keithley representative.

2-3. SYSTEM CONSIDERATIONS. The Control Unit is used in all configurations of the System I Calculator-Based Instrumentation System. It is recommended that the user determine the configuration to be used prior to placing the Control Unit in the System. The following factors should be considered:
a. Use of more than one Control Unit. The Control Unit has an internal switch (S103) which is set at the factory in CUl position, to designate the Control Unit as "Control Unit $l^{\prime \prime}$. If two Control Units are to be used in the System l, the Dual Control-Unit Coupler must be incorporated and the second Control Unit must be designated as CU2. If only one Control Unit is used, no modification of the Control Unit is needed. See Figure 5 for location of internal switch S103. TABLE 2-1.

Control Unit Useage in System 1

| Model No. | Number of Control <br> Units Needed | Dual Control- <br> Unit Coupler | Sl03 Setting |
| :---: | :---: | :--- | :--- |
| System 1/781 | 1 | Not Required. | CUl |
| System 1/782 | 2 | Required. <br> See Table 2-4. | First unit-CUl <br> Second unit-CU2 |

b. Use of two or more Scanners. If two or more Scanners are to be used in the System 1, the Multi-Scanner Coupler must be used with the Cantrol Unit. (See page 6-2.)
c. Use of more than one Instrument Interface. If more than one Instrument Interface is installed in a Control Unit at the same time, Model 7820-GPA 1/0 Handler Software must be used. See GUIDE TO USING THE SYSTEM 1 for system hardware and software requirements.

2-4. HOW TO INSTALL INTERFACES. (SERIES 7801, 7802, 7813)
a. Locations. The rear panel of the Control Unit has three plug-in compartments, identified as Tnterface Numbers 1, 2, and 3. These compartments can accept any Keithley Instrument interface or Accessory listed in Table 2-2.

TABLE 2-2.
Instrument Interfaces and Accessories Useable in the System 1

| Model No. | Name |
| :---: | :---: |
| Model 7801-160B/1602B | Instrument Interface |
| Model 7801-171/1712 | Instrument Interface |
| Model 7801-180/1802 | Instrument Interface |
| Model 7801-445 | Instrument Interface |
| Model 7801-616/6162 | Instrument Interface |
| Model 7802-110 | 8-Bit Isolated I/O Interface |
| Model 7813 | Interval Timer/Clock |
| Model 7802-C1K | Custom Interface Card |
| Model 7819-IEC | Interface Extender Card |

b. Installation. Any Keithley System I Interface will mate with any of the three plug-in compartments. Slide the Plug-in Card into the compartment with "component side" facing up. Make certain the card edges are aligned with the grooves in the compartment. When the card is fully inserted, the "locking tabs" on the card should be snapped into locking position as shown in Figure 3. On some Instrument Interfaces a switch setting must be made on the pc card prior to installing in the Control Unit. (See INSTRUCTION MANUAL, Instmument Interface.)
c. Removal. Unfasten "locking tabs" by pulling both tabs outward. Grasp the end of the card and pull out of chassis.

2-5. HOW TO RACK MOUNT THE CONTROL UNIT. The Control Unit is designed for 19 inch full rack mounting when used with the Model 1007 Rack Mounting Kit. The position of the Control Unit in a rack should be determined relative to the instruments or devices used in the System 1. For example, Series 7801 Instrument Interfaces have a 6 foot ( 2 m ) length cable which mates with a digital measuring instrument. Therefore considerations should be made for cable routing behind the rear panel. See page 6-1 for rack mounting information.

2-6. HOW TO APPLY POWER TO THE CONTROL UNIT.
a. How to set the Line Switch. The Control Unit has a single Line Switch which permits the user to select line voltage in three ranges. See Table 2-3.

## CAUTION

Remove line cord before changing switch positions.
TABLE 2-3.
Line Voltage Selection

| Position | Line Voltage | Fuse (Keithley Part No.) |
| :---: | :---: | :---: |
| $!\quad 90-110 \mathrm{~V}$ rms | $1 / 2 \mathrm{~A}(F U-4)$ |  |
|  | $105-125 \mathrm{~V} \mathrm{rms}$ | $1 / 2 \mathrm{~A}(\mathrm{FU}-4)$ |
|  | $210-250 \mathrm{~V} \mathrm{rms}$ | $1 / 4 \mathrm{~A}(\mathrm{FU}-17)$ |

b. Line Power. The Control Unit line power receptacle mates with Keithley line cord co-7 (furnished). The line cord is designed for use with three-prong receptacles having a grounded connection.


c. Power-Up Reset. When power is applied to the Control Unit a "Power-Up" reset is generated which causes all installed interfaces to go to their specific "power up" condition. The "power up" condition is listed in INSTRUCTION MANUAL, Instrument Interface, Series 7801, 7802 or 7813.

2-7. HOW TO USE REAR PANEL CONNECTORS (See Figure 2).
a. SCANNER Connector (P110). This connector is a 26-pin 3M Electro Products Division Part No. 3429. Pin 4 has been removed to admit a "polarizing key" on the mating System Interconnect Cable (Model 7021-2 or 7021-10).
b. TO PCU Cable (PI12). This five foot long cable is a 37 -conductor integrally mounted cable terminated by an ITT Cannon Part No. DC-37P male connector. The cable mates with a receptacle on Keithley PCU, Peripheral Coupler, or second Control Unit.
c. 2ND CONTROL UNIT (Spare opening). This opening is used when modifying a Control Unit for use in a System 17782. When shipped from the factory the Control Unit has a cover plate (part no. 26864) over the opening. When a Dual Control-Unit Coupler is installed on the Control Unit the cover plate must be removed and replaced with a 37-pin receptacle. See Table 2-4 and Figure 4.
d. INTERFACE NUMBER 1 (J103). This connector is a 50-pin card-edge type which mates with Series 7801 and 7802 Instrument Interfaces and Model 7813.
e. INTERFACE NUMBER 2 (J102). This connector is a 50-pin card-edge type which mates with Series 7801 and 7802 Instrument Interfaces and Model 7813.
f. INTERFACE NUMBER 3 ( J 101 ). This connector is a 50 -pin card-edge type which mates with Series 7801 and 7802 Instrument Interfaces and Model 7813.

TABLE 2-4.
How to Install the Dual Control-Unit Coupler

1. Disconnect power cord.
2. Remove cover plate over 2nd CONTROL UNIT opening.
3. Remove the Control Unit top cover.
4. Install 37 -pin receptacle using original screws used with cover plate.
5. Install Berg housing (8-pin) as shown in Figure 4.
6. Replace top cover.


FIGURE 5. Top View of Control Unit With Cover Removed.

## SECTION 3. INTERFACE CONSIDERATIONS

3-1. GENERAL. This section provides basic operating information concerning the interface bus and Scanner interface.

3-2. INTERFACE BUS CONFIGURATION. The Control Unit has three 50-pin card-edge connectors J101, J102, and J103 corresponding to Interface Numbers 3, 2, and 1. Except for Slot Address lines, all signals are wired in parallel on the three connectors. See Figure 6.

TABLE 3-1.
Summary of Signals on Interface Bus

| Name | Remarks |
| :---: | :---: |
| Slot Address (SA) | All three Slot address lines are wired to connectors J101, J102, and J103. Refer to Figure 6 for wiring. |
| 9VAC | This voltage is an auxiliary ac voltage used for certain Instrument Interfaces. |
| PWR UP RESET | This signal is generated when power is applied to the Control Unit. |
| CO, CI, C2 | These signals are Control commands. |
| CP (Control Pulse) | This signal is generated after a Control Byte has been received. |
| DP (Data Pulse) | This signal is generated after a Data Byte has been transferred. |
| RESET | This signal is generated for either of the following conditions: <br> RESET code is received from the PCU PWR UP RESET is generated |
| VCC | This is a +5 V logic supply for Interface logic. |
| GND | This is a logic supply "L0". |
| $\begin{aligned} & \text { DIH8, DIH4, DIH2, DIHI } \\ & \text { DIL8, DIL4, DIL2, DILI } \end{aligned}$ | These lines are the eight input data lines. Data which is to be sent to the PCU is applied to these lines. |
| $\begin{aligned} & B C 7, B C 6, B C 5, B C 4, \\ & B C 3, B C 2, B C 1, B C O \end{aligned}$ | These lines are outputs of the Byte Counter circuit. |
| $\overline{C P}$ (Control Pulse) | See CP above. |
| $\overline{\text { DP }}$ (Data Pulse) | See DP above. |
| RESET | See RESET above. |
| $\left.\begin{array}{l}\overline{\mathrm{DOH8}}, \overline{\mathrm{DOH4}}, \overline{\mathrm{DOH} 2}, \overline{\mathrm{DOHI}} \\ \overline{\mathrm{DOLB}}, \overline{\mathrm{DOL4}}, \overline{\mathrm{DOL}}, \overline{\mathrm{DOLT}}\end{array}\right\rangle$ | These lines are the eight data output lines. These lines represent data at the Output Register, except that the data has been inverted. |


| INTERFACE | CORRESPONDING | SIGNAL ON PINS* |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| NUMBER | CONNECTOR | 1 | 2 | 3 |  |
| 1 | $\mathrm{JlO3}$ | $\mathrm{SA}-1$ | $\mathrm{SA}-2$ | SA-3 |  |
| 2 | $\mathrm{JlO2}$ | $\mathrm{SA}-2$ | $\mathrm{SA}-3$ | $\mathrm{SA}-1$ |  |
| 3 | J 101 | $\mathrm{SA}-3$ | $\mathrm{SA}-2$ | $\mathrm{SA}-1$ |  |



FIGURE 6. Card-edge Connector (J101, J102, or J103).

## Control Unit

Model 780

3-3. SCANNER INTERFACE. The Scanner interface provides capability to control up to 8 Keithley Model 702/702X Scanners. The "SCANNER", connector is a 26 -pin connector that mates with a Series 7021 System Interconnect Cable. When used with a single Scanner, only one System Interconnect Cable is needed. If two or more Scanners are to be connected to a single Control Unit, a Multi-Scanner Coupler must be connected to the Control Unit. See Section 6, ACCESSORIES for detailed information on the use of the MultiScanner Coupler (Model 7819-MSC).

TABLE 3-2.
Connector ( $\mathrm{P} \mid \mathrm{IO}$ ) Pin Identification on the Control Unit

| Pin No. | Name | Remarks |
| :---: | :---: | :---: |
| 1 | CHAD 1 | CHannel ADdress Input |
| 2 | CHAD 4 | CHannel ADdress Input |
| 3 | Not Used | No Connection |
| 4 | Polarizing Pin | No Connection |
| 5 | LOCHAD 6 | LOad CHannel ADdress-Scanner \#6 |
| 6 | LOCHAD 7 | LOad CHannel ADdress-Scanner \#7 |
| 7 | LOCHAD 8 | LOad CHannel ADdress-Scanner \#8 |
| 8 | RELAY READY |  |
| 9 | REMOTE ALL OFF |  |
| 10 | Not Used | No Connection |
| 11 | Not Used | No Connection |
| 12 | LOCHAD 2 | LOad CHannel ADdress-Scanner \#2 |
| 13 | LOCHAD 4 | LOad CHannel ADdress-Scanner \#4 |
| 14 | CHAD 2 | CHannel ADdress Input |
| 15 | CHAD 8 | CHannel ADdress Input |
| 16 | LOCHAD 1 | LOad CHannel ADdress-Scanner \#1 |
| 17 | Not Used | No Connection |
| 18 | COMMON | Digital Common |
| 19 | COMMON | Digital Common |
| 20 | COMMON | Digital Common |
| 21 | COMMON | Digital Common |
| 22 | COMMON | Digital Common |
| 23 | Not Used | No Connection |
| 24 | Not Used | No Connection |
| 25 | LOCHAD 3 | LOad CHannel ADdress-Scanner \#3 |
| 26 | LOCHAD 5 | LOad CHannel ADdress-Scanner \#5 |



FIGURE 7. Scanner Connector (Pl|O) on Rear Panel.

TABLE 3-3.
Typical Logic Definitions Based on Manufacturers' Data

| Input Lines |  | Output Lines |  |
| :---: | :---: | :---: | :---: |
| LOGIC "1" <br> (Minimum) | LOGIC "O" <br> (Maximum) | $\begin{aligned} & \text { LOGIC "I" } \\ & \text { (Minimum) } \end{aligned}$ | LOGIC "0'" <br> (Maximum) |
| +2.0V | +0.8V | +2.4V | +0.4V |
| NOTE |  |  |  |
| Absolute maximum input voltage $=+5.25 \mathrm{~V}$ |  |  |  |
| Absolute minimum input voltage $=-0.5 \mathrm{~V}$ |  |  |  |

TABLE 3-4.
Standard Terminology Used For Logic Lines

| Symbol Name | Definition | Comments |
| :---: | :--- | :--- |
| $A B C$ | High True | True $=$ Logic " $1 " 1$ |
| $\overline{A B C}$ | Low True | True $=$ Logic ${ }^{\prime \prime} 0 "$ |

SECTION 4. THEORY OF OPERATION

4-1. GENERAL. The Control Unit contains circuitry which links the Programmable Calculating Unit (PCU) and all other System 1 instrumentation. This circuitry handles data transfers between the PCU and accessory interfaces or the built-in scanner interface.

4-2. CIRCUIT DESCRIPTION.
a. The circuitry can be divided into ten functional circuits.

1. Control/Data Byte Detector Circuit.
2. Output Control/Data Register Circuit.
3. Input Data Register Circult.
4. Indicator Circuit.
5. Control Byte Decoder Circuit.
6. Reset Circuit.
7. Control Byte One-Shot Multivibrator Circuit.
8. Data Byte One-Shot Multivibrator Circuit.
9. Byte Counter Circuit.
10. Scanner Interface Circuit.
b. Control/Data Byte Detector Circuit.
11. General Circuit Description. This circuit indicates whether a Control Operation (OPCB) or Data Operation (OPDB, IPDB) is being executed. Input signals are OTCT and $\overline{\text { DTEN. }}$
12. Detailed Circuit Description. When neither Control or Data operations are executed, $\overline{O T C T}$ and $\overline{D T E N}$ are a logic " 0 " during T8 to T15 of a machine cycle. When an OPCB instruction is executed, $\overline{O T C T}$ is at logic " 1 " during the entire machine cycle. When either an OPDB or IPDB instruction is executed, $\overline{D T E N}$ will remain a logic "ll" for the entire machine cycle (i.e. $\overline{D T E N}$ will not have a transition from logic "l" to logic '0'1).

## c. Output Control/Data Register Circuit.

I. General Circuit Description. This circuit is a serial in/parallel out Shift Register. Output control/data from the PCU is loaded into this register (U110) and clocked by $\phi 2$. BYOT is the serial input. BYOT is the inversion of signal BYOT.
2. Detailed Circuit Descmiption. When an output instruction (OPCB or OPDB) is executed, the contents of the Index Register is shifted into the Output Register. Output lines DOLI through DOHB are buffered and applied to the bus. If an OPCB instruction is executed the Control Byte Decoder is activated.

## d. Input Data Register Circuit.

1. General Circuit Description. This circuit is a parallel in/serial out Shift Register. Input data from the Control Unit is transferred to the PCU via this register. A byte ( 8 bits ) of data is serially transmitted to the PCU via BYIN, and clocked by $\phi 2$.
2. Detailed Circuit Description. Data input lines on the bus (DILI through DIH8) are shifted into the PCU Index Register and replace previous contents.
e. Indicator Circuit.
3. General Circuit Description. A total of 18 LED indicators are used on the Control Unit front panel to display data or status of control operations. The indicators are grouped as follows:
a) INPUT indicators ( L through H8). These indicators represent data to be transferred from the Control Unit to the PCU.
b) OUTPUT indicators (LI through H8). These indicators represent data which has been transferred from the PCU.
c) INSTRUCTION indicators. These indicators show whether the last $1 / 0$ instruction executed was a control operation (OPCB) or a data operation (OPDB or IPDB).
4. Detailed Circuit Description. All indicators are driven by two-input NAND gates.
a) INPUT indicators (LI through H8). Input data to be shifted into the PCU Index Register is displayed on indicators Ll through H8.
b) OUTPUT indicators. The data on the Output Control/Data Register is displayed on indicators LI through H8.
c) INSTRUCTION indicators. The NAND gates are connected to form an RS Flip-Flop.

The R and S inputs to the Flip-Flop are the two outputs of the Control/Data Byte
Detecter.
f. Control Byte Decoder Circuit.

1. General Circuit Description. This circuit accepts control information and decodes it into individual control signals. These signals are then used for controlling or transferring data to accessory instruments (when appropriate accessory Instrument Interface is installed).

## 2. Detailed Circuit Description.

a) PCU peripherals and the Control Unit are addressed using IH of an OPCB. Since $1 H$ is four bits wide, there are sixteen possible addresses, 0 through 15. System 1 uses two of sixteen possible addresses. Addresses 8 (binary 1000) and 9 (binary 1001) are used to address CUI and CU2 respectively. The address to which a Control Unit will respond is determined by the setting of S103, located on the Control Unit printed circuit board.
b) As mentioned above, the contents of the Output Control/Data Register is a copy of the Index Register after an output instruction has been executed. Of these outputs, DOHI through DOH8 represent the contents of IH. Execution of an OPCB instruction enables these bits to be applied to an address decoder. This decoder determines whether IH contains an eight or a nine depending on the position of the S103. The decoder's output will go high if IH contains a "one of us" code.
c) The low-order four bits of a Control Byte represent an operation code. If the address contained in $1 H$ is "one of us", that is an eight or nine, the DOLI through DOL8 data are latched into U120. The contents of IL are then decoded into Slot Addresses and Control signals. It is these signals which control the action of the instrument interface cards.
d) In addition to enabling the IL latch, the address decoder also sets an RS flipflop when iH contains a "one of us" code. The output of this flip-flop is used to enable BYIN so that data can be transferred to the PCU. When the address part of a Control Byte is not "one of us", the flip-flop is reset. This prevents our interface from interferring with other peripherals which might be connected to the PCU. g. Reset Circuit.

1. General Circuit Description. A RESET signal is generated under the following conditions:
a) Control Unit Power Up. When power is first applied to the Control Unit via the Power Switch, or disconnecting and reconnecting line power to the Control Unit with Power Switch set to ON.
b) PCU Reset. When a RESET command is generated at the PCU.
2. Detailed Circuit Description.
a) Control Unit Power Up. The RESET signal is applied to the bus and causes the following actions:
1) Clears Output Data Register.
2) Sets all accessory Instrument Interface circuitry to "Power-Up" condition. (See individual Instrument Interface Instruction Manual for detailed information.)
3) Clears control signals $\mathrm{CO}, \mathrm{Cl}$, and C 2 .
4) Disables BYIN (resets Flip-Flop).
5) Initiates a $\overline{\text { PWR UP RESET. }}$
b) PCU Reset. When a RESET command (OPCB and $I L=13_{10}$ ) occurs, the following actions result:
6) Output Data Register $=13_{10}$.
7) Sets all accessory Instrument Interface circuitry to "Power-Up" condition.
(See individual INSTRUCTION MANUAL for detailed information.)
8) Clears control signals $\mathrm{CO}, \mathrm{Cl}$, and C 2 .
9) Disables BYIN (resets Flip-Flop).
h. Control Byte One-Shot Multivibrator Circuits.
1. General Circuit Description. These circuits are used to synchronize transfer of control information within the Control Unit.
2. Detailed Circuit Description.
a) Ul3l. This One-Shot is fired at a logic "l" to logic " 0 " transition of the Control Byte Detector signal. This occurs at Tl5 of an OPCB instruction. The OneShot output enables the Address Decoder and Reset Command Detector.
b) Ul32. This One-Shot is fired at a logic "l" to logic " 0 " transition of the above one-shot and causes a Control Pulse (CP) on the bus.

## i. Data Byte One-Shot Multivibrator Circuit.

1. General Circuit Description. The output of this circuit is called Data Pulse (DP). This signal is similar to CP.
2. Detalled Circuit Description (Ull9). This One-Shot is fired at a logic "ll" to logic " 0 " transition of the Data Byte Detector signal, i.e. when elther IPDB or OPDB operations are executed.
L. Byte Counter Circuit.
I. General Circuit Description. This circuit generates eight control signals, BCO through $B C 7$, and are used as Strobe and Latch Enable functions.
3. Detailed Circuit Description. This circuit consists of a Decade Counter (Ul28) and a "One-out-of-Ten" Decoder (U129). When a Control Byte is detected, the Counter is reset to zero. The counter is incremented by DP. The Counter is wired so that when the counter is incremented beyond 7, the output is set to 9 . The Byte Counter outputs are available on the bus, and permits data byte transfer without the need for a Control Byte Command (i.e. after an IPDB or OPDB instruction is executed, the Byte Counter is incremented, enabling the next data byte).
$k$. Scanner Interface Circuit.
4. General Circuit Description. This circuit contains logic to control one Scanner (or up to 8 Scanners, when the Multi-Scanner Coupler is used). The logic is divided into three functional circuits.
a) REMOTE ALL OFF Logic. When a REMOTE ALL OFF command is initiated by the PCU, the Scanner interface logic generates a logic " 0 " on pin 9 of SCANNER connector.
b) LOCHAD Logic. The LOCHAD logic latches a LOCHAD code coming from the PCU. A logic " 0 " is generated on the appropriate LOCHAD line.
c) CHAD Buffer Logic. These buffer stages provide fan-out drive capability.
5. Detailed Circuit Description.
a) REMOTE ALL OFF Logic. Three logic gates (U121C, U118A, U123D) are used to generate a REMOTE ALL OFF command. The specific logic requirements for activating REMOTE ALL OF are given in Table 4-1.
table 4-I.
Logic for REMOTE ALL OFF

| INPUT |  |  |  |  |  | OUTPUT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { SCAN } \\ & \text { ADDR } \end{aligned}$ | Cl | U121-8 | $\overline{\mathrm{CP}}$ | U118-1 | RESET | REMOTE ALL OFF (Pin 9) |
| 1 | 1 | 0 | 0 | 1 | 0 | 0 (REMOTE ALL OFF activated) |
| 1 | 1 | 0 | 1 | 0 | 0 | 1 (REMOTE ALL. OFF not activated) |
| x | X | X | X | X | 1 | 0 (REMOTE ALL OFF activated) |

$x=$ Don't care
b) LOCHAD Logic. Five Logic gates are used with the Latch and Decoder. These gates control the operation of the latch and enable the LOCHAD buffers. Eight OR gates are used for buffering the LOCHAD outputs. When enabled, these gates apply the output of the decoder to the Scanners connected to the Control Unit.
c) CHAD Buffer Logic. The CHAD Buffer circuits (Ull3A, D, E, F) provide fan-out capability.

TABLE 4-2.
LOCHAD Lines Used on Scanner Connector

| Scanner Number | Pin Number |
| :---: | :---: |
| 1 | 6 |
| 2 | 16 |
| 1 | 12 |
|  | 5 |
| 6 | 13 |
| 7 | 26 |
|  | 7 |

TABLE 4-3.
Logic for LOCHAD Lines

| INPUT |  |  |  |  |  |  |  |  |  | OUTPUT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { SCAN } \\ & \text { ADDR } \end{aligned}$ |  | 21-11 |  |  | BCO | BCl | U121-6 | U108-10 | RESET |  |
| 1 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 1 | Latch enable is logic "l" |
| 1 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | Latch enable is logic "o" |
| X | $x$ | $x$ | X | X | X | X | X | X | 0 | Latch enable is logic "!" |
| 1 | 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | Lochad enable is logic "l" |
| 1 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | 1 | Lochad enable is logic "j" |

TABLE 4-4.
Illustration of Logic for CHAD Lines (Four of Ten Useable Combinations Shown)

| INPUT |  |  | OUTPUT |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\overline{\text { DOL8 }}$ | $\overline{\text { DOL4 }}$ | $\overline{\text { DOL }}$ | $\overline{\text { DOL }}$ | CHAD 8 | CHAD 4 | CHAD 2 | CHAD 1 |
| 1 | 1 | 1 | 0 | 0 | 0 | 0 | 1 |
| 1 | 1 | 0 | 1 | 0 | 0 | 1 | 0 |
| 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 | 1 | 0 | 0 | 0 |

TABLE 4-5.
reLay ready logic

| INPUT |  | OUTPUT |  |
| :---: | :---: | :---: | :---: |
| SCAN <br> ADDR | CO | U121-11 | U101-12 |
| 1 | 1 | 0 | 1 (RELAY READY enabled) |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 1 | 0 |
| 0 | 0 | 1 | 0 |

4-3. HOW TO INTERPRET THE FRONT PANEL INDICATORS. The Control Unit has 18 indicators as shown in Figure 8.

INPUT. These indicators represent data to be sent to the PCU from Interface Number 1, $\overline{2, \text { or }} 3$ or Scanner interface.
OUTPUT. These indicators represent data which has been received from the PCU.
The data represented by the indicators is sometimes in the form of two 8-4-2-1 BCD digits. Data from the PCU is represented in program memory as a three digit octal number from 000 to 377.


DATA CONTAOL
O
O

FIGURE 8. Front Panel Indicators.

## SECTION 5. MAINTENANCE

5-1. GENERAL. This section contains procedures for Performance Verification.
5-2. REQUIRED TEST EQUIPMENT. Recommended test equipment is given in Table 5-1. Test equipment other than recommended may be substituted if specifications equal or exceed the stated characteristics.

5-3. PERFORMANCE VERIFICATION. Use the following procedures to verify basic operation of the instrument (apart from any other component of the Keithley System lexcept the PCU). If the instrument is out of specification at any point, perform the troubleshooting check as in Section 5-4. In addition to test equipment a series 7810 1/0 Handler Software program will be needed.

TABLE 5-1.
Recommended Test Equipment Accessories Needed For Performance Verification

| Item | Name | Specification | Mfr. | Model |
| :---: | :--- | :--- | :--- | :--- |
| A | Oscilloscope | DC coupled, 4 channels, 2V \& 5V/div. <br> Sweep rate 50ms/div to 5us/div <br> External Triggering Capability | Tektronix | 560 |
| B | Programmable Calcu- <br> lating Unit | -11 Memory installed (minimum size) | KI | PCU |
| C | 1/0 Handler Software <br> (magnetic card) | Series 7810 | KI | Series <br> 7810 |

a. Initial Set-Up

1. Connect the PCU to line power, set Power $O N$, and set RUN/STEP/LOAD switch to RUN.
2. Set the Control Unit as described in Section 2-6 of this manual.
3. Plug the 37-pin connector from the Control Unit to the rear panel of the PCU.
4. Apply power to the Oscilloscope for measurements to follow. Specific settings will be given for each test.

NOTE
Wherever a test point on the circuit board is specified, the circuit designation of the circuit module (such as U103) is given followed by the pin number on that module or integrated circuit (example U103-12).
b. Test il. This test procedure checks the Control/Data Byte Detector under the condition that the PCU is executing no $1 / 0$ instructions. No program is needed for this test.

1. Ensure that the PCU is set to $O N$ and that the IDLE light is on.
2. Set the oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - $50 \mathrm{\mu s} / \mathrm{div}$.
c) Trigger Source - Channel 1, positive slope.
3. Make connections to the Control Unit circuitry as follows:
a) Connect Channel I Input to U103-12 (OTCT).
b) Connect Channel 2 Input to U103-11 (DTEN).
c) Connect Channel 3 Input to U103-8 (Control Detector output).
d) Connect Channel 4 Input to U103-9 (Data Detector output).
4. Verify that OTCT and DTEN are present as shown in figure 9.
5. Verify that Control Detector output and Data Detector output are at signal LO as shown in Figure 9.


FIGURE 9. Trace for Test \#1.
c. Test \#2. This test procedure checks the Control/Data Byte Detector outputs under the OPCB condition. A program is needed to obtain the OPCB condition.

1. Enter the program listed in Table 5-2. (See page 5-9.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the Oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - $50 \mu \mathrm{~s} / \mathrm{div}$.
c) Trigger Source - Channel 1 , positive slope.
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel 1 Input to U103-12 (OTCT).
b) Connect Channel 2 Input to U103-11 (DTEN).
c) Connect Channel 3 Input to U103-8 (Control Detector output).
d) Connect Channel 4 Input to U103-9 (Data Detector output).
5. Run the program beginning at branch point 00 .
6. Verify that OTCT is present except during each execution of an OPCB instruction (three consecutive OPCB instructions as in this example), as shown in Figure 10.
7. Verify that DTEN is present regardless of an OPCB instructions.
8. Verify that the Control Detector output goes to Logic "l" during each execution of an OPCB instruction.


FIGURE 10. Trace For Test \#2.
d. Test \#3. This test procedure checks the Control/Data Byte Detector outputs under the OPDB condition. A program is needed to obtain the OPCB condition.

1. Enter the program listed in Table 5-3. (See page 5-9.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the Oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - $50 \mu \mathrm{~s} / \mathrm{div}$.
c) Trigger Source - Channel 2, positive slope.
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel 1 Input to UlO3-12 (OTCT).
b) Connect Channel 2 Input to U103-11 (DTEN).
c) Connect Channel 3 Input to U103-8 (Control Detector output).
d) Connect Channel 4 Input to U103-9 (Data Detector output).
5. Run the program beginning at branch point 00.
6. Verify that DTEN is present except during each execution of a OPDB instruction (three consecutive $O P O B$ instructions as in this example), as shown in Figure 11.
7. Verify that OTCT is present regardless of a OPDB instruction.
8. Verify that the Data Detector output goes to Logic "l" during each execution of a OPDB instruction.


FIGURE 11. Trace for Test \#3.
e. Test \#4. This test procedure checks the Control/Data Byte Detector outputs under the IPDB condition. A program is needed to obtain the IPDB condition.

1. Enter the program listed in Table 5-4. (See page 5-9.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - $50 \mu \mathrm{~s} / \mathrm{div}$.
c) Trigger Source - Channel 2, positive slope.
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel 1 Input to U103-12 (OTCT).
b) Connect Channel 2 Input to U103-11 (DTEN).
c) Connect Channel 3 Input to U103-8 (Control Detector output)
d) Connect Channel 4 Input to Ul03-9 (Data Detector output)
5. Run the program beginning at branch point 00 .
6. Verify that DTEN is present except during each execution of a IPDB instruction (three consecutive IPDB instructions as in this example), as shown in Figure 12.
7. Verify that OTCT is present regardless of a IPDB instruction.
8. Verify that the Data Detector output goes to Logic "l" during each execution of a IPDB instruction.


FIGURE 12. Trace for Test \#4.
f. Test \#5. This test procedure checks the $\phi 2$ Enable Line. The $\phi 2$ Enable line, PCU clock line, and PCU BYOT line are used to control the operation of the Output Control/ Data Register. A program must be loaded into the PCU to obtain an OPCB condition.

1. Enter the program as listed in Table 5-5. (See page 5-9.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the Oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - $5 \mu \mathrm{~s} / \mathrm{div}$.
c) Trigger Source - Channel 1 , positive slope.
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel 1 Input to U107-10 ( $\phi 2$ Enable).
b) Connect Channel 2 Input to U107-9 ( $\phi 2$ ).
c) Connect Channel 3 Input to Ullo-1 (BYOT, Data Out)
5. Run the program beginning at branch point 00 .
6. Verify the traces shown in Figure 13.
NOTES.

Data is clocked into the Output Control/Data Register on the falling edge of $\phi 2$. Data is clocked with Ll being sent first. Ll to H8 is 10010101 binary.


FIGURE 13. Trace for Test \#5.
g. Test \#6. This test procedure checks the relationship between: Control Byte Detector Output and the two one shots associated with Control Bytes under the OPCB condition. A program must be loaded into the PCU to obtain the OPCB condition.

1. Enter the program listed in Table 5-6. (See page 5-9.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the Oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - IOus/div.
c) Trigger Source - Channel I, positive slope.
4. Make connections to the Control Unit circuitry as follows:
a) Connect channel 1 Input to Ul03-8 (Control Byte Detector output).
b) Connect Channel 2 input to U131-6 (Q output of Ist one-shot).
c) Connect Channel 3 Input to Ul32-6 (Control Pulse CP)
5. Run the program beginning at branch point 00 .
6. Verify the traces shown in Figure 14.
a) Q output of first one-shot should coincide with Logic "ll" to Logic "0"
transition of the Control Byte Detector output. (Synchronizes signals for the Control Unit.)
b) Q outfut of second one-shot should coincide with Logic "l" to Logic "0" transition of $Q$ output of first one-shot. (Synchronizes control signals for Instrument Interfaces.)


FIGURE 14. Trace For Test \#6.
h. Test \#7. This test procedure checks the relationship between: Data Byte Detector Output and the Data Pulse (DP) one-shot under the OPDB condition. A program must be loaded into the PCU to obtain the OPDB condition.

1. Enter the program listed in Table 5-7. (See page 5-9.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the Oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - 10 us/div.
c) Trigger Source - Channel 1, positive slope.
4. Make connections to the Model 780 circuitry as follows:
a) Connect Channel 1 Input to Ul03-9 (Data Byte Detector output).
b) Connect Channel 2 Input to U128-14 (Data Pulse DP).
c) Connect Channel 3 Input to U132-6 (Control Pulse CP).
5. Run the program beginning at branch point 00 .
6. Verify the traces shown in Figure 15.
a) Data Pulse should coincide with the Logic "ll" to Logic "0" transition of the Byte Detector Output.
b) Control Pulse does not appear (remains at Logic " 0 ").


FIGURE 15. Trace For Test \#7.

| Program |  |  | Table 5-2 |  |  |  | Test \#2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Need |  |  | rform |  |
| $\begin{aligned} & \text { DECIMAL } \\ & \text { STEP } \end{aligned}$ |  |  | INSTRUCTIONCODE |  |  |  | INSTRUCTION MNEMONIC |
| 0 | 00 | 0 | 3 | 1 | 4 | OPCB |  |
|  |  | 1 | 3 | 1 | 4 | OPCB |  |
|  |  | 2 | 3 | 1 | 4 | OPCB |  |
|  |  | 3 | 2 | 2 | 0 | JU00, | 000 |
|  |  | 4 |  | 0 |  |  |  |


| Table 5-3 |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Program Needed to Perform |  |  |  |  |  |  |
| $\begin{aligned} & \text { DECIMAL } \\ & \text { STEP } \end{aligned}$ |  | instruction CODE |  |  |  | INSTRUCTION MNEMONIC |
| 0 | 000 | 3 | 1 | 5 | OPDB |  |
|  | 1 | 3 | 1 | 5 | OPDB |  |
|  | 2 | 3 | 1 | 5 | OPDB |  |
|  | 3 | 2 | 2 | 0 | JUOO, | 000 |
|  | 4 | 0 | 0 |  |  |  |



## TABLE 5-6.

| Program Needed To Perform Test \#6 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} \text { DECIMAL } \\ \text { STEP } \end{gathered}$ |  | $\begin{gathered} \text { INSTRUCTION } \\ \text { CODE } \end{gathered}$ |  |  | instruction MNEMONIC |
|  | 000 | 2 | 6 | 6 | LDIX, 251 |
|  | 1 |  | 5 | 1 |  |
|  | 2 | 3 | 1 | 4 | OPCB |
|  | 3 | 2 | 2 | 0 | JU00, 000 |
|  | 4 |  | 0 |  |  |

## TABLE 5-7.

Program Needed to Perform Test \#7


STEP CODE MNEMONIC

```
0000 2 6 6 LDIX, 015
    10 1 5
    2 3 1 5 OPDB
    3 2 2 0 JUOO, 002
    400 2
```

i. Test \#8. This test procedure checks the Data Output Register and the Data Output lamp drivers. A series $78101 / 0$ Handler program (magnetic card) is needed to perform the test, as well as a specific keyboard entered program.

1. Enter a series $78101 / 0$ Handler program via the magnetic card reader at branch point 00 .
2. Enter the program listed in Table 5-8. (See page 5-13.)
3. Place the PCU in Program Mode.
4. Run the program beginning at branch point 00 .
5. Verify that the Data Output indicators (representing DOLI, DOL2, DOL4, DOL8, $\mathrm{DOHI}, \mathrm{DOH} 2, \mathrm{DOH} 4, \mathrm{DOH} 8$ ) are 1 ighted corresponding to a "walking one" moving towards the left. The Data Output lines $\overline{\mathrm{DOLT}}$ through $\overline{\mathrm{DOLD}}$ may also be observed. Since the data lines are inverted, a "walking zero" should be observed.
6. Enter the program listed in Table 5-9.
7. Place the PCU in Program Mode.
8. Run the program beginning at branch point 00.
9. Verify that the Data Output indicators (representing DOLI, DOL2, DOL4, DOL8, $\mathrm{DOH1}, \mathrm{DOH2}, \mathrm{DOH}^{2}, \mathrm{DOH} 8$ ) are lighted corresponding to a "walking zero" moving towards the left. The Data Output lines, $\overline{\mathrm{DOLT}}$ through $\overline{\mathrm{DOHE}}$ may also be observed. Since the data lines are inverted, a "walking one" should be observed.
j. Test \#9. This test procedure checks the Byte Counter circuitry using a static test. A program must be loaded into the PCU to obtain OPCB and OPDB conditions.
10. Enter the program listed in Table 5-10. (See page 5-13.)
11. Place the PCU in Program mode.
12. Set the oscilloscope as follows:
a) Vertical Sensitivity - 2 volts/div.
b) Horizontal Sweep - $50 \mathrm{~ms} / \mathrm{div}$.
c) Trigger Source - AUTO Trigger.
13. Make connections to the following Byte Count ( BC ) Iines at Interface Number I : $B C 0, B C 1, B C 2, B C 3, B C 4, B C 5, B C 6, B C 7$.
14. Run the program beginning at branch point 00.
15. Verify that the BCO line is at Logic "I" when the PCU "IDLE" indicator is lighted.
16. Depress RESUME.
17. Verify that BCI line is at Logic "l" when the PCU "IDLE" indicator is lighted.
18. Depress RESUME.
19. Verify that $B C 2$ line is at Logic "l" when the PCU "IDLE" indicator is lighted. NOTE

Continue the test in a similar fashion until $B C 7$ has been tested. Each time RESUME is depressed the program will cause the next BC line to go to Logic "l". After BC7 has been tested, all succeeding RESUME key strokes will have no effect on the BC lines (that is, all $B C$ lines will remain at Logic " 0 "'). The program may be run again by jumping to branch point 00.
k. Test \#10. This procedure checks the Byte Counter circuitry using a dynamic test. A program must be loaded into the PCU to obtain OPCB and OPDB conditions.

1. Enter the program listed in Table 5-11. (See page 5-13.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - DELAYED 50us/div.
c) Trigger Source - Channel 1 , positive slope.
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel 7 input to U128-14 (Data Pulse DP).
b) Connect Channel 2 input to U128-1 (QA on Data Byte Counter).
c) Connect Channel 3 input to U105-2 ( BCO ).
d) Connect Channel 4 input to U105-4 (BCI).
5. Run the program beginning at branch point 00.
6. Verify that $O A$ is toggled by the Logic "l" to Logic " 0 " transition of the Data Pulse (DP), thus incrementing the Byte Counter from BCO to BCI.
7. Change the oscilloscope connection on the Channel 4 Input from Ul05-4 to U103-8 (Control Byte Detector output).
8. Verify that $B C O$ is set to Logic " 1 " by the Logic " 0 " to Logic "l" transition of OPCB.


FIGURE 16. Trace For Test \#10.

1. Test \#11. This procedure checks the "one of us" decoder. This circuit is activated by a Control Byte with $H H=8$ or 9 depending on the position of Switch S103. A program must be loaded in the PCU to obtain an OPCB condition.
2. Set the Control Unit internal switch 5103 to CUl position.
3. Enter the program listed in Table 5-12. (See page 5-13.)
4. Set the RUN/STEP/LOAD switch on the PCU to RUN.
5. Set the oscilloscope as follows:
a) Vertical sensitivity - 5 volts/div.
b) Horizontal Sweep - 20us/div.
c) Trigger Source - Channel $\mid$ (negative slope).
6. Make connections to the Control Unit circuitry as follows:
a) Connect Channel 1 to U131-1 ( $\bar{Q}$ of first CTRL one-shot).
b) Connect Channel 2 to U107-11 (one of us).
c) Connect Channel 3 to U118-13 (Latch Enable).
d) Connect Channel 4 to Ull8-10 (BYIN Enable).
7. Run the program beginning at branch point 00 .
8. Verify the traces shown in Figure 17.


FIGURE 17. Trace For Test \#ll.

TABLE 5-8.
Program Needed to Perform Test \#8 (Part 1) DECIMAL STEP

INSTRUCTION
CODE
0000
266
LDIX, 001
1001
$\begin{array}{lllll}2 & 3 & 1 & 5 & O P D B\end{array}$
$\begin{array}{lllll}3 & 3 & 4 & 7 & S L C I\end{array}$
$41160 \quad$ STIO
50001011
61107 WAIT
$\begin{array}{lllll}7 & 1 & 6 & 1 & \text { RCIO }\end{array}$
$8 \quad 220$ JU00, 002
$9 \quad 0 \quad 0 \quad 2$
INSTRUCTION MNEMONIC

TABLE 5-10.
Program Needed to Perform Test \#9

## DECIMAL

 STEP INSTRUCTION CODEINSTRUCTION
MNEMONIC
0000
314
OPCB
1056 HALT
$231 \begin{array}{llll}2 & 3 & 5 P D B\end{array}$
30556 HALT
4220 JUOO, 002
$5 \quad 0 \quad 0 \quad 2$

TABLE 5-9.

```
Program Needed To Perform Test #8 (Part 2)
DECIMAL INSTRUCTION INSTRUCTION CODE MNEMONIC
```




```
            1.376
```

            1.376
            2 3 1 5 5 OPDB
            2 3 1 5 5 OPDB
            3 3}
            3 3}
            4 1 6 0 ST1O
            4 1 6 0 ST1O
            5 0 0 1 "1"
            5 0 0 1 "1"
            6 1 0 7 WAIT
            6 1 0 7 WAIT
            7 1 6 1 RCIO
            7 1 6 1 RCIO
            8 2 2 0 JU00, 002
            8 2 2 0 JU00, 002
            9 0 0 2
    ```
            9 0 0 2
```

TABLE 5-11.
Program Needed to Perform Test \#10 dECIMAL INSTRUCTION INSTRUCTION STEP CODE MNEMONIC

```
0}00000\mp@code{2 6 6 LDIX, 200
            1 2 0 0
                2
            3 3 1 5 5 OPDB
            4 3 1 5 OPDB
            5 3 1 1 5 OPDB
            6 3 1 5 OPDB
            7 2 2 0 JUOO, 000
            8000
```

TABLE 5-12.
Program Needed to Perform Test \#11

| OECIMAL | INSTRUCTION |  |
| :---: | :---: | :---: |
| STEP | CODE | INSTRUCTION |
| MNEMONIC |  |  |

$0000 \quad 266$ LDIX, 200
1200
2314 OPCB
$3 \quad 341 \quad 1 C 1 H$
4314 OPCB
52220 JUOO, 000
6000

TABLE 5-13.
Program Needed to Perform Test \#12

| $\underset{\text { DECIMAL }}{\text { STEP }}$ | INSTRUCTION <br> CODE | INSTRUCTION <br> MNEMONIC |
| :---: | :---: | :---: |


| 0 | 0 | 0 | 0 | 2 | 6 | 6 | LDIX, 200 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  |  | 1 | 2 | 0 | 0 |  |  |
|  |  |  | 2 | 3 | 1 | 4 | OPCB |  |
|  |  | 3 | 3 | 4 | 0 | ICIL |  |  |
|  |  | 4 | 0 | 5 | 6 | HALT |  |  |
|  |  | 5 | 2 | 2 | 0 | JUOO, | 002 |  |

$6 \quad 0 \quad 0 \quad 2$
m. Test \#12. This procedure checks the Control Byte Operation Decoder. The Control Byte operation Decoder decodes the IL portion of Control Byte. A program must be loaded into the PCU to obtain an OPCB condition.

1. Enter the program listed in Table 5-13. (See page 5-13.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the oscilloscope as follows:
a) Vertical Sensitivity - 2 volts/div.
b) Horizontal Sweep - $50 \mathrm{~ms} / \mathrm{div}$.
c) Trigger Source - AUTO Trigger.
4. Run the program beginning at branch point 00.
5. Make a connection between Channel I Input and the following pins on Interface Number 1: 1 (SA1), 2 (SA2), 3 (SA3), 13 (CO), 19 (C1), 17 (C2) and U121-10 (SCAN ADDR) on the Model 780 pc board.
6. Verify that the signals in Table 5-14 are at Logic " 11 " depending on the contents of IL. Each time RESUME is depressed another Control Byte will be sent out of the PCU and the contents of $I L$ will be incremented by one. After $I L=15$, the program loops to $1 L=0$.
NOTE

The operation codes above a decimal 10 are not presently used by the Control Unit, except 13 (RESET) which is $1 H$ independent. TABLE 5-14.
Summary of Signal Condition

| ACTION | (BASE 10) |  |  | STATUS OF SIGNAL LINES |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | IL CONTENTS | SAI | SA2 | SA3 | CO | Cl | C2 | SCAN | ADDR |
| Run Program | 0 | 1 | $\times$ | $x$ | 1 | $x$ | X |  | X |
| Depress Resume | 1 | $x$ | 1 | $\times$ | 1 | $\times$ | x |  | $x$ |
| Depress Resume | 2 | x | $x$ | 1 | 1 | $\times$ | $x$ |  | $\times$ |
| Depress Resume | 3 | $\times$ | $\times$ | $x$ | 1 | $\times$ | x |  | 1 |
| Depress Resume | 4 | 1 | $\times$ | $x$ | $x$ | 1 | $x$ |  | $x$ |
| Depress Resume | 5 | $\times$ | 1 | $\times$ | X | 1 | $\times$ |  | X |
| Depress Resume | 6 | $\times$ | $x$ | 1 | $\times$ | 1 | $x$ |  | $\times$ |
| Depress Resume | 7 | $\times$ | $x$ | $x$ | X | 1 | $\times$ |  | 1 |
| Depress Resume | 8 | 1 | $\times$ | $x$ | X | $\times$ | 1 |  | $x$ |
| Depress Resume | 9 | $\times$ | 1 | $\times$ | X | x | 1 |  | $\times$ |
| Depress Resume | 10 | $\times$ | $x$ | 1 | $x$ | $\times$ | 1 |  | $\times$ |
| Depress Resume | 11 | $\times$ | $\times$ | $\times$ | $\times$ | $x$ | 1 |  | 1 |
| Depress Resume | 12 | 1 | $\times$ | $\times$ | X | $x$ | $x$ |  | $\times$ |
| Depress Resume | 13 | $x$ | 1 | $\times$ | $x$ | X | $x$ |  | $\times$ |
| Depress Resume | 14 | $x$ | $\times$ | 1 | $x$ | $x$ | $x$ |  | $\times$ |
| Depress Resume | 15 | $\times$ | $\times$ | $\times$ | X | $\times$ | $\times$ |  | I |
| Depress Resume | 0 | 1 | $\times$ | $\times$ | 1 | X | x |  | $\times$ |
| $x=$ Don't Care |  |  |  |  |  |  |  |  |  |

n. Test \#13. This test procedure checks the BYIN Enable Flip-Flop. A program must be loaded into the PCU to obtain an OPCB condition.

1. Enter the program listed in Table 5-15. (See page 5-19.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the oscilloscope as follows:
a) Vertical Sensitivity 2 volts/div.
b) Horizontal Sweep - $100 \mu \mathrm{~s} / \mathrm{div}$. (MAIN TIME BASE) 50 $\mathrm{us} / \mathrm{div}$. (DELAYED SWEEP)
c) Trigger Source - Channel 1 (Negative slope).
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel I Input to $U 118-10$ (BYIN Enables $F / F Q$ output).
b) Connect Channel 2 Input to U107-1 (RESET).
5. Run the program beginning at branch point 00.
6. Verify that output of BYIN F/F is:
a) Set by a valid "one of us" code.
b) Reset by a $\overline{R E S E T}$ signal.


FIGURE 18. Trace For Test \#13.
o. Test \#14. This test procedure checks the $1 H$ Independent RESET Code Detector. This circuit detects Control Bytes with $I H=$ don't care ${ }^{\prime \prime}$ and $I L=15$ octal, such as RESET Control Byte. A program must be loaded into the PCU to obtain an OPCB condition.

1. Enter the program listed in Table 5-16. (See page 5-19.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - $100 \mu \mathrm{~s} / \mathrm{div}$. (MAIN TIME BASE) 50 $\mathrm{s} / \mathrm{s} / \mathrm{div}$. (DELAYED SWEEP)
c) Trigger Source - Channel 1 (Negative Slope).
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel I Input to U114-6 (Reset Code Detector output).
b) Connect Channel 2 Input to U104-2 (First CTRL one-shot $\bar{Q}$ ).
c) Connect Channel 3 Input to Ul04-1 (Reset Signal to OR Gate).
5. Run the program beginning at branch point 00.
6. Verify traces shown in Figure 19.


FiGURE 19. Trace For Test \#14.
p. Test \#15. This test procedure checks the Power Up Reset circuitry. This circuitry operates when power is first applied to the Control Unit. Both a RESET and a POWER UP RESET pulse is generated. No program is needed for this test. (No PCU connection is needed).

1. Set the oscilloscope as follows:
a) Vertical Sensitivity - Channel 1: 2 volts/div. Channel 2: I volt/div.
b) Horizontal Sweep - $50 \mathrm{~ms} / \mathrm{div}$.
c) Trigger Source - See below for suggested settings using an oscilloscope with storage capability.
2. Make connections to the Control Unit circuitry as follows:
a) Connect Channel I Input to U114-8 (Power Up Reset output).
b) Connect Channel 2 Input to Ul14-9 (Input from RC circuit).
3. Set the oscilloscope to SINGLE SWEEP mode.
4. Manually start the sweep with the LEVEL control.
5. Turn on the Control Unit Power Switch when the sweep reaches the approximate center of the screen.
6. Verify a Power-Up Reset signal on Channel 1 as shown in Figure 20.


FIGURE 20. Trace For Test \#15.
q. Test \#16. This test procedure checks the RESET and RESET lines. A program must
be loaded into the PCU to obtain an OPCB condition.

1. Enter the program listed in Table 5-17. (See page 5-19.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - 50 us/div. (MAIN TIME BASE) lous/div. (DELAYED SWEEP)
c) Trigger Source - Channel 1 , positive slope.
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel 1 Input to U101-8 (RESET).
b) Connect Channel 2 Input to U104-13 ( $\overline{\text { RESET }}$ ).
c) Connect Channel 3 Input to U104-2 (First CTRL One-Shot $\bar{Q}$ ).
5. Run the program beginning at branch point 00.

NOTE
The program will run continuously. Depress RESET to stop the program.
6. Verify that the FIRST CTRL one-shot $\bar{Q}$ goes to Logic " 0 " when RESET goes to Logic "l", as shown in Figure 21.


FIGURE 21. Trace For Test \#16.

TABLE 5-15.
Program Needed to Perform Test \#13

| DECIMAL | INSTRUCTION | INSTRUCTION |
| :---: | :---: | :---: |
| STEP | CODE | MNEMONIC |

$0000 \quad 266 \quad$ LDIX, 200
1200
$\begin{array}{llllll}2 & 3 & 1 & 4 & \text { OPCB } & \\ 3 & 2 & 6 & 6\end{array} \quad$ LDIX, 015
$4 \quad 0 \quad 1 \quad 5$
$5 \quad 314$ OPCB
6220 JU00, 2000
7000

TABLE 5-16.
Program Needed to Perform Test \#14

| DECIMAL INSTRUCTION | INSTRUCTION |  |
| :---: | :---: | :---: |
| STEP | CODE | MNEMONIC |

00002666 LDIX, 200
1200
$\begin{array}{lllll}2 & 3 & 1 & 4 & O P C B\end{array}$
$3 \quad 2666$ LDIX, 015
40015
$\begin{array}{lllll}5 & 3 & 1 & 4 & O P C B\end{array}$
6220 JUOO, 000
7000 MNEMONIC

| 00 | 0 | 0 | 2 | 6 | 6 | LDIX, 200 |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | 1 | 2 | 0 | 0 |  |  |  |
|  |  | 2 | 3 | 1 | 4 | OPCB |  |  |
|  |  | 3 | 2 | 6 | 6 | LDIX, 015 |  |  |
|  |  | 4 | 0 | 1 | 5 |  |  |  |
|  |  | 5 | 3 | 1 | 4 | OPCB |  |  |
|  |  | 6 | 2 | 2 | 0 | JUOO, 000 |  |  |
|  |  |  |  | 0 | 0 | 0 |  |  |

TABLE 5-17.
Program Needed to Perform Test \#16
DECIMAL INSTRUCTION INSTRUCTION STEP CODE MNEMONIC $\begin{array}{llllllll}0 & 0 & 0 & 0 & 2 & 6 & 6 & \mathrm{LDIX}, 015\end{array}$

1015
$\begin{array}{llllll}2 & 3 & 1 & 4 & O P C B & \\ 3 & 2 & 2 & 0 & J \cup O O, & 000\end{array}$
4000

TABLE 5-19.
Program Needed to Perform Test \#18
DECIMAL INSTRUCTION INSTRUCTION CODE MNEMONIC
$00000 \quad 2666 \quad \mathrm{LDIX}, 000$
1000
$2 \quad 3 \quad 1 \quad 5 \quad O P D B$
$3 \quad 340 \quad 1 C I L$
4056 HALT
$5 \quad 220$ JUOO, 002
6002

```
0
            1 2 0 0.\cdots
            2. % 1 4 OPCB
            3 2 0 0 BROO, 015
            4015
            5 2 6 6 LDIX, 204
            6 2 0 4
                    7 
                    8 2 0 0 BRO0, 015
                    9 0
                            1 0 2 6 6 LDIX, 210
                            1 1 2 1 0
                            1
                            1 3}0
                            1442 6 6 LDIX, 015
                            1 5}0001
                            1 6
                                    17 0 5 6 HALT
                                    1 8 3 7 1 1 RCLP
                            19 3 7 1 RCLP
```

r. Test \#17. This test procedure checks the CO, C1 and C2 lines.* A program must be loaded into the PCU to obtain an OPCB condition.

1. Enter the program listed in Table 5-18.
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Run the program beginning at branch point 00.
4. Verify that SAI and CO are set to Logic "l".
5. Depress RESUME. A RESET will be sent out.
6. Verify that $C O$ is set to Logic ' 0 '".
7. Depress RESUME.
8. Verify that SAl and Cl are set.
9. Depress RESUME.
10. Verify that RESET is sent out and Cl is reset.
11. Depress RESUME.
12. Verify that $S A 1$ and $C 2$ are set.
13. Depress RESUME.
14. Verify that RESET is sent out and $C 2$ is reset.
15. To run the program again, jump to branch point 00 and RESUME.
*NOTE
These 1 ines can be examined on connector J 101 , J 102 , or J 103 as shown in Figure 6 , page 3-2.
s. Test \#18. This test procedure tests the Scanner interface circuitry (CHAD lines). A program must be loaded into the PCU.
16. Enter the program listed in Table 5-19. (See page 5-19.)
17. Set the RUN/STEP/LOAD switch on the PCU to RUN.
18. Set the Oscilloscope as follows:
a) Vertical Sensitivity - 2 volts/div.
b) Horizontal Sweep - $2 \mathrm{~ms} / \mathrm{div}$.
c) Trigger Source - Channel 1
19. Connect Channel l to the "TO SCANNER" connector at the various CHAD lines indicated in Table 5-20.
20. Run the program beginning at branch point 00.

NOTE
The program steps through the 16 possible combinations of addresses in binary sequence (mod 16). Verify that front panel indicators and CHAD lines are as given in Table 5-20.

TABLE 5-20.
Summary of CHAD Testing

| Program Action | OUTPUT <br> Indicators |  |  |  |  |  |  |  |  | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Start Program | 0 | 0 | 0 | 0 |  | 0 | 0 | 0 | 0 | Channel 0 selected |
| RESUME | 0 | 0 | 0 | 1 |  | 0 | 0 | 0 | 1 | Channel 1 selected |
| RESUME | 0 | 0 | 1 | 0 |  | 0 | 0 | I | 0 | Channel 2 selected |
| RESUME | 0 | 0 | 1 | 1 |  | 0 | 0 | 1 | 1 | Channel 3 selected |
| RESUME | 0 | 1 | 0 | 0 |  | 0 | 1 | 0 | 0 | Channel 4 selected |
| RESUME | 0 | 1 | 0 | 1 |  | 0 | 1 | 0 | 1 | Channel 5 selected |
| RESUME | 0 | 1 | 1 | 0 |  | 0 | 1 | 1 | 0 | Channel 6 selected |
| RESUME | 0 | 1 | 1 | 1 |  | 0 | 1 | 1 | 1 | Channel 7 selected |
| RESUME | 1 | 0 | 0 | 0 |  | 1 | 0 | 0 | 0 | Channel 8 selected |
| RESUME | 1 | 0 | 0 | 1 |  | 1 | 0 | 0 | 1 | Channel 9 selected |
| RESUME | 1 | 0 | 1 | 0 |  | , | 0 | 1 | 0 | No Channel |
| RESUME | 1 | 0 | 1 | 1 |  | 1 | 0 |  | 1 | No Channel |
| RESUME | 1 | 1 | 0 | 0 |  | , | 1 | 0 | 0 | No Channel |
| RESUME | 1 | 1 | 0 | * 1 |  | , | 1 | 0 | 1 | No Channel |
| Resume | 1 | 1 | 1 | 0 |  | , | , | , | 0 | No Channel |
| RESUME | 1 | 1 | 1 | 1 | $\bigcirc$ | 1 | 1 | 1 | 1 | No Channel |

t. Test \#19. This test procedure tests the Scanner interface circuitry (LOCHAD lines), except for gates U126 and U127. A program must be loaded into the PCU. (No Scanner needs to be connected.)

1. Enter the program listed in Table 5-21. (See page 5-22.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the Oscilloscope as follows:
a) Vertical Sensitivity - 2 volts/div.
b) Horizontal Sweep - $2 \mathrm{~ms} / \mathrm{div}$.
c) Trigger Source - AUTO trigger
4. Connect Channel 1 to the "SCANNER' connector at the various LOCHAD lines indicated in Table 5-22.
5. Run the program beginning at branch point 00.

NOTE
The program can be used to step through all eight LOCHAD commands. Verify that the logic on the appropriate LOCHAD line is as given in Table 5-22. Also verify that the correct indicators are lighted.

NOTE
Part 2 of Test \#19 is continued on page 5-23.

TABLE 5-21.


TABLE 5-22.
Summary of Test Points Used in Test \#19.

| Scanner LOCHAD Line | U125 <br> Logic Levels |  |  |  |  |  |  |  | "SCANNER" Connector Pllo | OUTPUT Indicators |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 2 | 3 | 4 | 5 | 6 | 7 | 9 | 10 | Pin No. | L8 | 1.4 | L2 | L1 |
| 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 16 | 0 | 0 | 0 | 0 |
| 2 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 12 | 0 | 0 | 1 | 0 |
| 3 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 25 | 0 | 0 | 1 | 1 |
| 4 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 13 | 0 | 1 | 0 | 0 |
| 5 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 26 | 0 | 1 | 0 | 1 |
| 6 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 5 | 0 | 1 | 1 | 0 |
| 7 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 6 | 0 | 1 | 1 | 1 |
| 8 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 7 | 1 | 0 | 0 | 0 |

Part 2 of Test \#19
6. Enter the program listed in Table 5-23.
7. Set the RUN/STEP/LOAD switch on the PCU to RUN.
8. Set the Oscilloscope as follows:
a) Vertical Sensitivity - 2 volts/div.
b) Horizontal Sweep - 10us/div.
c) Trigger Source - Channel 1 , positive slope.
9. Connect Channel 1 to the "SCANNER" connector at the various LOCHAD lines indicated in Table 5-22.
10. Run the program beginning at branch point 00 .
11. Verify the waveform shown in Figure 22. (See page 5-24.)

NOTE
The program runs continuously. To halt the program, depress RESET. The program has been written specifically for LOCHAD 1 only. To test the remaining 7 LOCHAD lines the program must be altered. For example, to test LOCHAD 2, change location 0004 to code 002 instead of code 001.

TABLE 5-23.
Program Needed to Perform Test \#19 (Part 2)
DECIMAL INSTRUCTION INSTRUCTION STEP CODE MNEMONIC

| 0 | 0 | 0 | 0 | 2 | 6 | 6 | LDIX, 203 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | 1 | 2 | 0 | 3 |  |  |  |
|  |  | 2 | 3 | 1 | 4 | OPCB |  |  |
|  |  | 3 | 2 | 6 | 6 | LDIX, 001 |  |  |
|  |  | 4 | 0 | 0 | 1 |  |  |  |
|  |  | 5 | 3 | 1 | 5 |  | OPDB |  |
|  |  | 6 | 3 | 1 | 5 | OPDB |  |  |
|  |  | 7 | 2 | 2 | 0 | JUOO, 000 |  |  |
|  |  | 8 | 0 | 0 | 0 |  |  |  |



FIGURE 22. Trace For Test \#19 (Part 2).
4. Test \#20. This test procedure checks the Scanner interface circuitry (Latch Enable). A program must be loaded into the PCU to obtain OPCB and OPD8 conditions.

1. Enter the program listed in Table 5-24. (See page 5-28.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the Oscilloscope as follows:
a) Vertical Sensitivity - 5 volts/div.
b) Horizontal Sweep - $200 \mu \mathrm{~s} / \mathrm{div}$. (MAIN TIME BASE) 50 $\mathrm{m} / \mathrm{div}$. (DELAYED SWEEP)
c) Trigger Source - Channel 1 , positive slope.
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel 1 Input to U104-6 ( $\overline{\mathrm{DP}}$ ) .
b) Connect Channel 2 Input to U117-2 (CO • SCAN ADDR).
c) Connect Channel 3 Input to U121-5 (BCO).
d) Connect Channel 4 Input to U108-10 (Latch Enable).
5. Run the program beginning at branch point 00 .
6. Verify that Latch Enable is at Logic "l" under the following conditions:
a) CO • SCAN ADDR is at Logic "l".
b) BCO is at Logic " $l$ ".
c) $\overline{D P}$ is at Logic " 0 ".

V. Test \#21. This test procedure checks the Scanner interface circuitry (LOCHAD Enable). A program must be loaded into the PCU to obtain OPCB and OPDB conditions.
7. Enter the program listed in Table 5-24 (same program used in Test No. 20).
8. Set the RUN/STEP/LOAD switch on the PCU to RUN.
9. Set the Oscilloscope as in Test No. 20.
10. Make connections to the Control Unit circuitry as follows:
a) Connect Channel. I Input to U104-6 ( $\overline{\mathrm{DP}}$ ) .
b) Connect Channel 2 Input to U117-2 (CO • SCAN ADDR).
c) Connect Channel 3 Input to U121-1 (BCI).
d) Connect Channel 4 Input to U121-3 (LOCHAD Gate Enable).
11. Run the program beginning at branch point 00.
12. Verify that LOCHAD Gate Enable is at Logic "O" under the following conditions:
a) CO • SCAN ADDR is at Logic "1".
b) BCl is at Logic "l".
c) $\overline{D P}$ is at Logic " 0 ".


FIGURE 24. Trace For Test \#21.
w. Test \#22. This test procedure is used to check the Input Data Register. A program must be loaded into the PCU to obtain OPCB and IPDB conditions.

1. Enter the program listed in Table 5-25 (See page 5-28.)
2. Set the RUN/STEP/LOAD switch on the PCU to RUN.
3. Set the 0scilloscope as follows:
a) Vertical Sensitivity - Channel 1, 2: 5 volts/div. Channel 3: 2 volts/div.
b) Horizontal Sweep - 50 $\mathrm{s} / \mathrm{div}$. (MAIN TIME BASE) 5us/div. (DELAYED SWEEP)
c) Trigger Source - Channel l, positive slope.
4. Make connections to the Control Unit circuitry as follows:
a) Connect Channel 1 Input to Ul09-1 (Data Byte Detector Output).
b) Connect Channel 2 Input to U109-2 (PCU Clock Signal).
c) Connect Channel 3 Input to U108-11 (PCU Byte Input Line).
5. Run program beginning at branch point 00 .
6. Verify traces shown in Figure 25.

The OPCB instruction sends out a Control Byte with 200 code. This is a "one-of-us" code and sets the BYIN Flip-Flop to enable the BYIN line. The data being applied to the INPUT REGISTER is (L.1 to H8) 01001011 binary.


FIGURE 25. Trace For Test \#22.

TABLE 5-24.

|  |  | Needed INSTRUCTION CODE |  |  | Perform Test \#20 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | instru MNEM |
| 0 | 000 |  |  |  |  | 6 |  | LDIX | 203 |
|  | 1 |  | 0 |  |  |  |
|  | 2 |  | 1 |  | OPCB |  |
|  | 3 |  | 1 |  | OPDB |  |
|  | 4 |  | 1 |  | OPDB |  |
|  | 5 |  | 6 |  | LDIX | 200 |
|  | 6 |  | 0 |  |  |  |
|  | 7 |  | 1 |  | OPCB |  |
|  | 8 |  | 2 |  | JU00, | 000 |
|  | 9 |  | 0 |  |  |  |

TABLE 5-25.
Program Needed to Perform Test \#22
DECIMAL INSTRUCTION
STEP
CODE
MSTRUCTION
MNEMONIC

0000266 LDIX, 200
1200
$2314 \quad O P C B$
$3 \quad 305$ IPDB
4305 IPDB
5220 JU00, 003
6003

## SECTION 6. ACCESSORIES

6-1. RACK MOUNTING KIT. (Similar to hardware supplied with Model 1007 Rack Mounting Kit) a. General. The rack mounting hardware furnished with the instrument permits standard 3-1/2 in. $\times 19 \mathrm{in}$. rack mounting, $15-1 / 2 \mathrm{in}$. ( 395 mm ) depth behind the front panel. The hardware included consists of two angle brackets and extra mounting screws.
b. Installation Instructions.

1. Remove the "side dress" panels on both sides of the instrument as follows:
a) Remove two screws ( $\# 6-32 \times 1 / 4$ ) on each side of the instrument.
b) Slide the "side dress" panels toward the rear of the instrument to remove.
2. Install an "angle bracket" (Item 21) on each side using longer screws (1tems 22 and 28) in place of original screws (a total of three screws is needed per side).

TABLE 6-1.
Parts List For Rack Mounting Kit

| Item <br> No. | Description | Qty <br> Req'd | Keithley <br> Part No. |
| :---: | :--- | :---: | :---: |
| 21 | Angle Bracket | 2 | 274108 |
| 22 | Screw, \#6-32 $\times 5 / 8$, Phillips | 4 | -- |
| 28 | Screw, \#6-32 $\times 1 / 2$, Phlllips | 2 | -- |



FIGURE 26. Rack Mounting of the Control Unit.

6-2. MULTI-SCANNER COUPLER (Model 7819-MSC).
a. General. The Multi-Scanner Coupler provides additional connections for up to 8 Scanners. $1 / 0$ Handler Software, furnished with any Series 7801 Instrument Interface, Series 7802 , or Model 7813 , may be used to control multiple Scanners connected to the MSC.

1. A single Model 7021-10 System Interconnect Cable is furnished with the MSC to couple to the Control Unit.
2. In addition, the MSC provides eight connectors which mate with any System Interconnect Cable (furnished with each Scanner).
3. A set of slide switches enable the user to modify the Scanner interconnections if necessary. When set to NORMAL, only one active Scanner at a time is permitted.

NOTE
Each switch conncets the Scanner VCH line (pin 24) to a "VCH bus", when set to NORMAL (ON). If it is desired to use the System 1 for parallel-channel or matrix operation refer to EN DOOZAMYMG $\because E C H I Q U E S$. The $1 / 0$ Handler program must be altered to nermit parallel-channel solections since the software routine sends out a REMOTE ALL JFF sianal prior to executing a new channel address. See also schematic 273570 in Section 7 of this manual.


FIGURE 27. Multi-Scanner Coupler (Model 7819-MSC). SPECIFICATIONS

GENERAL: Couples single scanner output connector of Model 780 to eight connectors for controlling up to eight Model 702 Scanners. Total length (sum) of all scanner interconnection cables must not exceed 40 feet.
MIJLTIPLE-CHANHEL SELECT: Scanner interconnections prevent inadvertent selection of multiple channels. This protection feature can be defeated by switches on Mode! TOl9-MSC, permitting one channel on each scanner to be Grlected for arallel-channel or matrix operation.
SIZE. WEIGHT: 2 in. high $\times 9$ in. wide $\times 3-1 / 2 \mathrm{in}$. deep ( $50 \times 230 \times 90 \mathrm{~mm}$ ).
le: weight, $1-1 / 4$ pounds $(0,6 \mathrm{~kg})$.
ACCESSORIES FURNISHED: MOdel 7021-10 cable, 10 ft . ( 3 m ) long.

## b. How to Install the MSC.

1. Connect a System Interconnect Cable (Model 7021-2 or Model 7021-10) between SCANNER on the Control Unit and TO 780 CONTROL UNIT on the MSC.
2. Connect Scanner 1 DIGITAL INPUT and SCANNER 1 input on the MSC, Scanner 2 DIGITAL INPUT and SCANNER 2 input on the MSC, etc.

NOTE
Total length (sum) of all scanner interconnection cables must not exceed 40 feet. 3. Set all slide switches on the MSC to NORMAL.


FIGURE 28. Typical System 1 Multi-Scanner Connection.

6-3. INTERFACE EXTENDER CARD (Model 7819-IEC). This Interface Card is a System 1 compatible plug-in board that mates with a card-edge connector at Interface Number 1, 2, or 3 on a Control Unit. It permits operation of an Interface (Series 7801) or special-purpose card (Series 7802 and 7813) external to the Model 780 for troubleshooting and repair.

6-4. CUSTOM INTERFACE (Model 7802-CIK).
a. The Custom Interface Card is a System 1 compatibie plug-in board for constructing custom interfaces. Provision is made for accessibility to input, output, and control signals ( $T T L$ ) on the Control Unit.
b. The printed circuit board accepts up to 20 sixteen-pin wire-wrapped DIP sockets. All internal and external connections are terminated in pads for wire-wrappable post insertion.
c. Power is available from the Control Unit to supply logic power. Circuit tapes are provided for power and ground distribution.
d. Due to the card structure the CIK can be installed at Interface Number 3 or Interface Number 1 (if Interface Number 2 is empty). Clearance for wire-wrappable pins prohibits installation of a cik in Interface Number 2.
e. Typical mating components which may be used with the Model 7819-CIK include the following.

1. Wire-wrappable 14-pin DIP socket, Amphenol part no. 82120013-144 (not furnished).
2. Wire-wrappable 16-pin DIP sockets, Amphenol part no. 82120013-164 (not furnished).
3. PC-mountable 50-pin ribbon-cable header, Keithley part no. CS-311 (not furnished).
4. Wirewrappable terminals, Vector T44-1 (not furnished).

NOTE
No active electronic components are furnished with the cIk.

SPECIFICATIONS, MODEL 7802-CIK

GENERAL: PC board for convenient construction of custom interfaces. Provides access to System 1 input, output, and control signals (TTL).
COMPONENT MOUNTING: PC board accepts up to 20 sixteen-pin wire-wrappable DIP sockets. All internal and external connections terminated in pads for wirewrappable post insertion.
CONNECTORS:
INTERNAL: 50-pin gold-plated card edge mates with connector in Model 780
Control Unit.
EXTERNAL: Provision for PC mounting of 50 conductor ribbon-cable header ( $3 M^{R}$ Model $3426-0000$ ), or metal mounting plate may be machined to accept a connector.
POWER AVAILABLE: Logic power; +5 volts referenced to PCU ground, 0.5 amperes maximum. Power and ground are distributed on board.
SIZE, WEIGHT: $4-1 / 2 \mathrm{in} . \times 9 \mathrm{in} .(115 \times 230 \mathrm{~mm})$ printed circuit card. Depth with wire-wrappable posts installed limits mounting to slot 3 in Model 780 , and slot 1 if slot 2 is not used. Net weight, 3 ounces ( 85 g ).
ACCESSORIES FURNISHED: Card latch/pull assembly and external connector mounting plate are attached.

## f. Limitations on Signal Lines.

l. Output Lines. In general, each Output line can drive a maximum of three TTL loads. The Slot Address (SA) lines can drive up to eight TTL loads. If more drive capability is needed, a buffer can be used, consisting of two 7404 Series inverters connected in series.
2. Input Lines. The data Input lines must be driven with open collector gates. Use 7401 Series Quad 2-Input NAND gates for DIL2 through DIH8. Use a power gate such as an MC858 to drive DILI. The data input line drivers must be disabled when they are not actively driving the lines.

NOTE
Pull-up resistors are furnished on the pc board in the Control Unit for DILI-DIH8 lines.
g. Limitations on +5 V Power Supply. The Model $7802-\mathrm{ClK}$ may draw a maximum of 0.5 ampere.
h. Custom Interface Design. Since an interface used with the System 1 involves both $1 / 0$ Handler Software and interface circuitry (hardware), the designer should be thoroughly familiar with contents of the following manuals.

1. INSTRUCTION MANUAL, Control Unit, Model 780
2. PCU PROGRAMMING TECHNIQUES
3. PCU ADVANCED PROGRAMMING

NOTE
An interface design such as any series 7801 Interface may be used as an example when designing a custom interface.
6-5. DUAL CONTROL UNIT COUPLER (Model 7819-DCC). The DCC is a field-installable accessory that may be used to expand any System 1 for use with two Control Units. The DCC provides a 37 -pin connector into which a second Control Unit may be plugged. (See pages 2-4 and 2-5 for detailed installation instructions.)


7-1. GENERAL. This section contains information for ordering replacement parts. The parts list is arranged in alphabetical order of their Circuit Designations.

7-2. ORDERING INFORMATION. To place an order or to obtain information concerning replacement parts, contact your Keithley representative or the factory. See the inside front cover of the catalog for addresses. When ordering, include the following information.
a. Instrument Model Number
b. Instrument Serial Number
c. Part Description
d. Circuit Designation (if applicable)
e. Keithley Part Number.

## 7-3. SCHEMATICS.

a. Control Unit, PC-383, PC-395. Schematic Number 27007E describes all Control Unit circuitry including the Scanner interface.
b. Instrument interfaces. Schematics for all accessory interfaces are found in the individual INSTRUCTION MANUAL for Series 7801, 7802, and 7813 interfaces.
c. Multi-Scanner Coupler (Model 7819-MSC). Schematic 27357D

TABLE 7-1.
PC Board Designation Series

| Series | Description | Designation | Page No. |
| :---: | :--- | :--- | :---: |
| 100 | Control Unit, Logic | PC-395 | $7-5$ |
| 600 | Display Board | PC-383 | $7-5$ |

TABLE 7-2.
Mechanical Parts List

| $\begin{aligned} & \text { I tem } \\ & \text { No. } \\ & \hline \end{aligned}$ | Description | Qty. Per Assembly | Keithley <br> Part No. | Figure No. |
| :---: | :---: | :---: | :---: | :---: |
| - | Chassis Assembly | - | -- | 30 |
| - | Front Panel Assembly | - | -- |  |
| 1 | Front Panel | 1 | 26860C |  |
| 2 | Screw, Slotted, 6-32 $\times 3 / 8$ | 4 | -- |  |
| 3 | Front Panel Overlay | 1 | 26865 C |  |
| 4 | Rear Panel | 1 | 26892 C |  |
| 5 | Side Extrusion Left | 1 | 24378B |  |
| 6 | Side Extrusion Right | 1 | 24378B |  |
| 7 | Corner Bracket | 2 | 247458 |  |
| 8 | Screw, Socket, $6-32 \times 1 / 4$ | 4 | --- |  |
| 9 | Screw, Phillips, 6-32 $\times 1 / 4$ | 4 | -- |  |
| 10 | Clip for Side Dress | 2 | FA-101 |  |
| 11 | Side Dress Panel | 2 | 243608 |  |
| - | Top Cover Assembly | - | -- | 30 |
| 12 | Top Cover | 1 | 26875 C |  |
| 13 | Screw, Socket, 6-32 5/16 | 4 | -- |  |
| 4 | Bottom Cover Assembly | - | 272648 | 30 |
| 14 | Bottom Cover | 1 | 27263 C |  |
| 15 | Screw, Socket, 6-32 5 5/16 | 4 | -- |  |
| - | Feet Assembly | - | -- |  |
| 16 | Molded Foot | 4 | 24322B |  |
| 17 | Rubber Foot | 4 | FE-6 |  |
| 18 | Tilt Bail | 1 | 147048 |  |
| 19 | Screw, Phillips, 6-32 | 4 | -- |  |
| 20 | Kep Nut, 6-32 | 4 | -- |  |



FIGURE 30. Chassis Assembly

TABLE 7-3.
Cross-Reference of Manufacturers

| ABREV. | NAME AND ADDRESS | AbREV. | NAME AND ADDRESS |
| :---: | :---: | :---: | :---: |
| A-B | Allen-Bradley Corp. Milwaukee, WI 53204 | KI | Keithley Instruments, Inc. Cleveland, OH 44139 |
| ALCO | Alco Electronic Products, Inc. North Andover, MA 01845 | MALL | Mallory Capacitor Indianapolis, IN 46206 |
| BERG | Berg Electronics, Inc. New Cumberland, PA 17070 | MOLEX | Molex <br> Downers Grove, IL. 60515 |
| BUSS | Bussmann Mfg. Div. <br> St. Louis, MO 63107 | MOT | Motorola Semiconductor Products <br> Phoenix, AZ 85008 |
| c-w | ```Continental-Wirt Electronics Corp. Warminster, PA 18974``` | NAT | National Semiconductor Corp. <br> Santa Clara, CA 95051 |
| CAN | ITT Cannon Electric <br> Santa Ana, CA 92702 | REI | Richey Electronics, Inc. Nashville, TN 37213 |
| CENLB | Centralab Division Milwaukee, WI 53201 | S-C | Switcheraft, Inc. Chicago, IL 60630 |
| COMPI | Components, Inc. Beddeford, ME 04005 | SIG | Signetics Corp. <br> Sunnyvale, CA 94086 |
| ECI | Electrocube Inc. <br> San Gabriel, CA 91776 | SOL | Solitron Devices, Inc. Tappan, NY 10983 |
| ERIE | Erie Technological Products, Inc. Erie, PA 16512 | TEXAS | Texas Instruments, Inc. Dallas, TX 75231 |
| H-P | $\begin{aligned} & \text { Hewlett-Packard } \\ & \text { Palo Alto, CA } 94304 \end{aligned}$ | 3M | 3M Company Headquarters <br> St. Paul, MN 55101 |


| Circuit Desig. | Description | Mfr. Code | Mfr. Desig. | Keithley Part No. | Qty. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C 101 | $10000 \mu \mathrm{~F}, 15 \mathrm{~V}$. . . . . . | MALL | TCG103U015N3C3P | C-266-10000M | 1 |
| C 102 | $0.47 \mu \mathrm{~F}, 20 \mathrm{~V}, \mathrm{ET} . .$. | COMPI | TDI-20-474-20 | C-179-0.47M | 2 |
| C 103 | $0.47 \mu \mathrm{~F}, 20 \mathrm{~V}, \mathrm{ET}$. | COMPI | TDI-20-474-20 | $\mathrm{C}-179-0.47 \mathrm{M}$ | - |
| C104 | $100 \mu \mathrm{~F}, 15 \mathrm{~V}, \mathrm{EAL}$ | REI | JC6100158P | C-210-100M | 1 |
| C105 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$ | CENLB | UK16-104 | C-238-0.01M | 10 |
| C 106 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$. | CENLB | UK16-104 | C-238-0.01M | - |
| C107 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$. | CENLB | UK16-104 | C-238-0.01M | - |
| Cl08 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$ | CENLB | UK16-104 | $\mathrm{C}-238-0.01 \mathrm{M}$ | - |
| C109 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$ | CENLB | UK16-104 | $\mathrm{C}-238-0.01 \mathrm{M}$ | - |
| C110 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$ | CENLB | UKI6-104 | $\mathrm{C}-238-0.01 \mathrm{M}$ | - |
| Clll | $22 \mu \mathrm{~F}, 20 \mathrm{~V}, \mathrm{ET}$. | COMPI. | TDI-20-226-20 | C-179-22M | 1 |
| C112 | $0.0022 \mu \mathrm{~F}, 500 \mathrm{~V}, \mathrm{CerD}$. | ERIE | 831-25U0-222M | C-22-0.0022M | 2 |
| C 113 | $0.0022 \mu \mathrm{~F}, 500 \mathrm{~V}, \mathrm{CerD}$. | ERIE | 831-25U0-222M | $\mathrm{C}-22-0.0022 \mathrm{M}$ | - |
| C114 | $0.01 \mu \mathrm{~F}, 50 \mathrm{~V}$, Metal Poly Carbonate | ECI | 625 Bl A | $\mathrm{C}-201-0.01 \mathrm{M}$ | 3 |
| C115 | $0.01 \mu \mathrm{~F}, 50 \mathrm{~V}$, Metal Poly Carbonate | ECI | 62581 A | $\mathrm{C}-201-0.01 \mathrm{M}$ | - |
| C 116 | $0.01 \mu \mathrm{~F}, 50 \mathrm{~V}$, Metal Poly Carbonate | ECI | 625B1A | C-201-0.01M | - |
| C117 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$. . | CENLB | UK16-104 | C-238-0.01M | - |
| C118 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$. | CENLB | UK16-104 | C-238-0.01M | - |
| C119 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$. | CENLB | UK16-104 | C-238-0.01M | - |
| C120 | $0.01 \mu \mathrm{~F}, 16 \mathrm{~V}, \mathrm{CerD}$ | CENLB | UK16-104 | C-238-0.01M | - |
| C121 | 680 pF, 1000V, CerD. . . . . . ${ }^{\text {dio }}$ | CENLB ES | DD-681 | C-64-680P | 1 |
| Circuit Desig. | Description | Mfr. Code | Mfr. Desig. | Keithley Part No. | Qty. |
| CR101 | Rectifier, 3A, 50 V (1N4139) | SOL | 3450 | RF-34 | 2 |
| CR102 | Rectifler, 3A, 50V (1N4139) | SOL | 3 A 50 | RF-34 | - |
| CR103 | Rectifier, $75 \mathrm{~mA}, 75 \mathrm{~V}$ | TEXAS | 1 N 914 | RF-28 | 3 |
| CR104 | Rectifier, $75 \mathrm{~mA}, 75 \mathrm{~V}$ | TEXAS | 1 N 914 | RF-28 | - |
| CR105 | Rectifier, $75 \mathrm{~mA}, 75 \mathrm{~V}$. . | TEXAS | 1 N914 | RF-28 | - |

DIGITAL DISPLAY

| Circuit Desig. | Description |  | Mfr. <br> Code | Mfr. Desig. | Keithley Part No. | Qty. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DS601 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP 5082-4494 | PL-63 | 18 |
| DS602 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP 5082-4494 | PL-63 | - |
| DS603 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP 5082-4494 | PL-63 | - |
| DS604 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP 5082-4494 | PL-63 | - |
| DS605 | Pilot Light | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP 5082-4494 | PL-63 | - |

## DIGITAL DISPLAY (Cont'd)

| Circuit Desig. | Description |  | Mfr. Code | Mfr. Desig. | Keithley <br> Part No. | Qty. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DS606 | Pilot Light, | Light Emitting Diode | H-P | HP 5082-4494 | PL-63 | - |
| DS607 | Pilot Light, | Light Emitting Diode | H-P | HP5082-4494 | PL-63 | - |
| DS608 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP5082-4494 | PL-63 | - |
| DS609 | Pilot Light, | Light Emitting Diode | H-P | HP5082-4494 | PL-63 | - |
| DS610 | Pilot Light, | Light Emitting Diode | H-P | HP5082-4494 | PL-63 | - |
| DS611 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP5082-4494 | PL-63 | - |
| DS612 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP5082-4494 | PL-63 | - |
| DS613 | Pilot Light, | Light Emitting Diode | H-P | HP5082-4494 | PL-63 | - |
| DS614 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP5082-4494 | PL-63 | - |
| DS615 | Pilot Light, | Liaht Emitting Diode | H-P | HP5082-4494 | PL-63 | - |
| DS616 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP5082-4494 | PL-63 | - |
| DS617 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP5082-4494 | PL-63 | - |
| DS618 | Pilot Light, | Light Emitting Diode | $\mathrm{H}-\mathrm{P}$ | HP5082-4494 | PL-63 | - |

FUSE


| Circuit | Mfr. | Mfr. | Keithley |
| :--- | :--- | :--- | :--- |
| Desig. | Description | Code | Desig. |


| J 101 | Card Edge | 3 M | 3415-0000 | CS-294-2 | 3 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $J 102$ | Card Edge | 3M | 3415-0000 | CS-294-2 | - |
| J103 | Card Edge | 3 M | 3415-0000 | CS-294-2 | - |
| $J 104$ | Connector, 2-pin, Female. | MOLEX | 2139-2 | CS-275 | 1 |
| $J 105$ | Receptacle, 3-pin, Female | MOLEX | 2139-3 | CS-287-3 | 2 |
| J106 | Receptacle, 3-pin, Female | MOLEX | 2139-3 | CS-287-3 | - |
| J107 | Housing, Mini PV, 10-pin. | BERG | 65039-C | CS-310 | 1 |
| J601 | Receptacle, 10-pin. | BERG | 20052 | CS-237 | 2 |
| J602 | Receptacle, 10-pin. | BERG | 20052 | CS-237 | - |
| P101 | Not Used. | $\cdots$ | . |  | - |
| P102 | Not Used. | . . | . |  | - |
| P103 | Not Used. | . ${ }^{\text {a }}$ | . | $\cdots$ | - |
| P104 | Receptacle, 2-pin | molex | A-2391-2A | CS-288-2 | 1 |
| P105 | Receptacle, 3-pin | MOLEX | A-2391-3A | CS-288-3 | 1 |
| P106 | Receptacle, $4-\mathrm{pin}$ | MOLEX | A-2391-4A | CS-288-4 | 1 |
| P107 | Male Pin. | KI |  | 24249A | - |
| P103 | Male Pin. | KI |  | 24249 A | - |


| Circuit Desig. | Description | Mfr. <br> Code | Mfr. Desig. | Keithley Part No. | Qty. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| P109 | Male Pin. | KI | -• | 24249A | - |
| P110 | Receptacle, 26-pin, "SCANNER". | KI | Modified CS-295-1 | 26744A | - |
| P\\|ll | Receptacle, 3-pin, "LINE PONER" | $\mathrm{S}-\mathrm{C}$ | EAC 301 | CS-254 | 1 |
| P112 | Connector, 37-pin, Female | CAN | DC-37P | CS-302 | 1 |
| P113 | Male Pin. . . . . . . | KI | . . | 24249A | - |

TRANSISTORS

| Circuit Desig. | Description | Mfr. <br> Code | Mfr. Desig. | Keithley Part No. | Qty. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Q101 | PNP Transist | MOT | 2N5875 | TG-114 | 1 |

RESISTORS


## RESISTORS (Cont'd)



## SWITCHES

| Circuit Desig. | Description | Mfr. <br> Code | Mfr. Desig. | Keithley Part No. | Qty. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| S 101 | Toggle Switch, "POWER" | ALCO | MSTZ05N | SW-271 | 1 |
| S102 | Slide Switch, "LINE SETTING". | S-C | 11D-1139 | SW-273 | 1 |
| S103 | Slide Switch DPDT, "CUl/CU2". | C-W | GG-350-PC-DPDT | SW-385 | 1 |

TRANSFORMER

| Circuit | Mfr. | Mfr. |
| :--- | :--- | :--- |
| Desig. | Description | Code |

T101 Power Transformer, Center-Tapped Secondary . . . . . . . . . . . KI TR-162

## INTEGRATED CIRCUITS

| Circuit Desig. | Description | Mfr. Code | Mfr. Desig. | Keithley Part No. | Qty. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| U101 | Hex Inverters TTL, 14-Pin DiP | TEXAS | SN7404N | 1c-33 | 6 |
| U102 | Hex Inverters TTL, 14-Pin DIP | TEXAS | SN7404N | 1c-33 | - |
| U103 | Positive NOR Gates, 14-Pin DIP. | TEXAS | SN7402N | 1c-32 | 5 |
| U104 | Positive NOR Gates, 14-Pin DIP. | TEXAS | SN7402N | 1c-32 | - |
| U105 | Hex Inverters TTL, 14-Pin DIP. | TEXAS | SN7404N | IC-33 | - |

INTEGRATED CIRCUITS (Cont'd)

| Circuit Desig. | Description | Mfr. Code | Mfr. Desig. | Keithley <br> Part No. | Qty. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 4106 | Hex Inverters TTL, 14-Pin DIP | TEXAS | SN7404N | 1--33 | - |
| 4107 | ```Positive NAND Gates, Quad 2-Input, 14-Pin DIP.``` | TEXAS | SN7400N | 1C-38 | 2 |
| U108 | Quad NAND Gate, 14-Pin DIP. . . . | MOT | MC858P | $1 \mathrm{C}-52$ | 6 |
| U109 | ```Parallel-Load 8-Bit Shift Register, 16-Pin DIP.``` | SIG | N74165 | 1C-123 | 1 |
| U110 | 8-Bit Parallel Out, Serial Shift Registers, 14-Pin DIP . . . . . | TEXAS | SN74164J | 1C-119 | 1 |
| U111 | Quad NAND Gate, 14-Pin DIP. . . | MOT | MC858p | 1-52 | - |
| U112 | Quad NAND Gate, 14-Pin DIP. | MOT | MC858P | IC-52 | - |
| U113 | Hex Inverters TTL, 14-Pin DIP | texas | SN7404N | IC-33 | - |
| U114 | Dual NAND Schmitt Trigger, 14-Pin DIP |  | N7413A | 1C-121 | 1 |
| U115 | Quad NAND Gate, 14-Pin DIP. | MOT | MC858P | 10-52 | - |
| 4116 | Quad NAND Gate, 14-Pin DIP. | MOT | MC858P | 1c-52 | - |
| 0117 | Quad NAND Gate, 14-Pin DIP. | MOT | MC858P | 1C-52 | - |
| U118 | Positive NOR Gates, 14-Pin DIP. | TEXAS | SN7402N | IC-32 | - |
| U119 | ```Monostable Multivibrator, 14-Pin DIP``` | TEXAS | SN74121N | 1C-118 | 3 |
| U120 | Bistable Latches, 16-Pin DIP. . | TEXAS | SN7475N | 1C-36 | 2 |
| Ul21 | Positive NAND Gates, Quad 2-Input, 14-Pin DIP. | TEXAS | SN7400N | IC-38 | - |
| U122 | Positive NOR Gates, 14-Pin DIP. | TEXAS | SN7402N | 1C-32 | - |
| U123 | Positive NOR Gates, 14-Pin DIP. | TEXAS | SN7402N | IC-32 | - |
| U124 | Bistable Latches, 16-Pin DIP. . | TEXAS | SN7475N | IC-36 | - |
| U125 | BCD/Decimal decoder, 16-Pin DIP | TEXAS | SN7442 | IC-51 | 2 |
| U126 | Quad, 2-Input OR, 14-Pin DIP. | SIG | N7432A | 1c-115 | 2 |
| 4127 | Quad, 2-Input OR, 14-Pin DIP. | SIG | N7432A | IC-115 | - |
| U128 | Decode Counters, 14-Pin DIP | TEXAS | SN7490N | IC-37 | 1 |
| U129 | BCD/Decimal decoder, 16-Pin DIP | TEXAS | SN7442 | 1c-51 | - |
| U130 | Hex Inverters TTL, 14-Pin DIP | TEXAS | SN7404N | IC-33 | - |
| 4131 | Monostable Multivibrator, $14 m$ Pin DIP | TEXAS | SN74121N | 16-118 | - |
| U132 | Monostable Multivibrator, 14-Pin DIP | TEXAS | SN74121N | IC-118 | - |

## VOLTAGE REGULATOR

| Circuit | Mfr. Mfr. | Keithley |
| :--- | :--- | :--- |
| Desig. | Description | CodeDesig.$\quad$Part No. Qty. |

VR101 5 volt Regulator, T0-3 Case . . . NAT LM309K I

End of Section 7
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SECTION 7

FIGURE 31．Component Layout For PC－395．
Circuit Location Circuit Location Desig $\begin{array}{ll}\text { R114 } & \mathrm{H}-3 \\ & \mathrm{G}-4\end{array}$ $\begin{array}{ll}\text { R115 } & \text { G－4 } \\ \text { R11 } & \text { F－4 }\end{array}$
 0
$\frac{0}{1} \frac{0}{4}$
$\frac{1}{\alpha}$ 0
4
4 L 6
$\infty$
$\infty$
$\vdots$号
号
 no mum
$\vdots$
un
4 mu


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